ThomasGodden

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Design Engineering student at Imperial College London with an extensive background in competitive robotics, as well as work experience in mechanical and systems engineering. I love to work on complex, high power or moonshot problems, particularly ones involving autonomous systems with interesting planning, dynamics and control aspects.

Education

Second-year Design Engineering (MEng) student at Imperial College London.

Expected Graduation: 2023

Relevant coursework: Computing, Electronics: Signals, Systems and Control, Engineering Mathematics, Solid Mechanics, Production and Materials, Industrial Design Engineering, FEA, Physical Computing

Employment

Spacebit: Contract Analysis

2021

Analysis work on the UK's first mission to the moon

Dyson School of Design Engineering: Maths Module Placement and Teaching Assistant

2020

- Redesigned and rebuilt the module problem sheet framework to fit better with an online learning environment
 Simplexity Product Development: <u>Mechanical engineering intern</u>
 2018, 2019
 - Designed a cost-effective linear motion control testbed, with swappable motors and controllers
- Did mechanical, electrical, and pneumatic assembly as well as redesign work for biotech assembly fixtures

Rancho Bernardo Community Presbyterian Church: <u>Tech assistant, Head lighting designer</u>

2015 - 2019

Project and Team Experience

Imperial College Hyperloop: Electronics and Control Systems

2021 - present

- Leading the development and production of a 50kW+ traction inverter system for a linear induction motor.
- Imperial College Robotics Society: <u>Chief Lab Manager</u>

2020 - present

- Lab manager of a student-run makerspace operating within the EEE department of Imperial College London.
- Coordinated with the department to move into a newly-renovated lab space

Imperial College London Eurobot Team: <u>Team Lead</u>

2020 - present

- Remotely led a team of students to build a fully autonomous competition robot running the ROS framework.
- Worked on CAD design, ROS, Localization, Planning, Networking and Computer Vision systems.

Imperial College London Advanced Rocket Recovery: <u>Design and Control Systems</u>

2019 - 2020

Design for an experimental drone project, attempting to recover a model rocket while still in-flight.

FIRST Tech Challenge team 10092: Team lead, Mechanical lead

2015 - 2019

- Coordinated a team of 15 middle and highschool students to design, manufacture and program competitive robots that went on to compete and win awards at an international level
- Developed a trajectory recording and following algorithm for a skid steer robot that allowed for autonomous navigation at similar velocities and accuracies to driver operated control

FIRST Robotics Competition team 6995: Controls Software Lead

2019

- Designed and tuned the control software for the lift on a 120lb competitive robot which was part of the winning alliance at the 2019 San Diego regional
- Developed and tuned a computer vision-based auto-alignment and scoring routine

Research with Dr. Hugo Pedro at the University of California San Diego

2018 - 2019

• Developed a web-based machine learning system for generating and presenting solar power forecasts using existing weather data

Engineering Skills

Proficient: PTC Creo \\ Solidworks \\ Onshape \\ Python \\ Java \\ Git and Github \\ 3D printing \\ Project management and team coordination \\ ROS \\ Embedded Systems Development (STM32F and Arduino)

Familiar: Fusion 360 \\ MATLAB and Simulink \\ Linux \\ C/C++ \\ Julia \\ Machine Learning \\ Bond graph systems modeling \\ Systems Control and Optimization \\ Web development \\ UI design \\ Machining and manufacturing